

Spatial-Temporal Union of Subspaces for Multi-body NRSFM: Supplementary Material

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Abstract. This paper provides a detailed derivation to the solutions and statistical data of the results provided in [2].

1 Detailed derivation of the solution

1.1 Solution for S

$$\begin{aligned} \mathbf{S} = \operatorname{argmin}_{\mathbf{S}} & \frac{1}{2} \|\mathbf{W} - \mathbf{R}\mathbf{S}\|_{\mathbb{F}}^2 + \langle \mathbf{Y}_1, \mathbf{S}^\sharp - \mathbf{g}(\mathbf{S}) \rangle + \frac{\beta}{2} \|\mathbf{S}^\sharp - \mathbf{g}(\mathbf{S})\|_{\mathbb{F}}^2 + \langle \mathbf{Y}_2, \mathbf{S} - \mathbf{S}\mathbf{C}_1 \rangle \\ & + \frac{\beta}{2} \|\mathbf{S} - \mathbf{S}\mathbf{C}_1\|_{\mathbb{F}}^2. \end{aligned}$$

We are minimizing this equation w.r.t \mathbf{S} . Therefore, we convert the second and third term in the above equation to the dimension of \mathbf{S} .

$$\mathbf{S}^\sharp = \mathbf{g}(\mathbf{S}) \Rightarrow \mathbf{S} = \mathbf{g}^{-1}(\mathbf{S}^\sharp) \text{ (linear mapping).}$$

Similarly, Lagrange multiplier \mathbf{Y}_1 is mapped to the dimension of \mathbf{S} .

$$\begin{aligned} \mathbf{S} = \operatorname{argmin}_{\mathbf{S}} & \frac{1}{2} \|\mathbf{W} - \mathbf{R}\mathbf{S}\|_{\mathbb{F}}^2 + \frac{\beta}{2} \|\mathbf{g}^{-1}(\mathbf{S}^\sharp) - \mathbf{S}\|_{\mathbb{F}}^2 + \langle \mathbf{g}^{-1}(\mathbf{Y}_1), \mathbf{g}^{-1}(\mathbf{S}^\sharp) - \mathbf{S} \rangle \\ & \langle \mathbf{Y}_2, \mathbf{S} - \mathbf{S}\mathbf{C}_1 \rangle + \frac{\beta}{2} \|\mathbf{S} - \mathbf{S}\mathbf{C}_1\|_{\mathbb{F}}^2. \\ = \operatorname{argmin}_{\mathbf{S}} & \frac{1}{2} \|\mathbf{W} - \mathbf{R}\mathbf{S}\|_{\mathbb{F}}^2 + \frac{\beta}{2} (\|\mathbf{g}^{-1}(\mathbf{S}^\sharp)\|_{\mathbb{F}}^2 + \|\mathbf{S}\|_{\mathbb{F}}^2 - 2\operatorname{Tr}((\mathbf{g}^{-1}(\mathbf{S}^\sharp))^T \mathbf{S}) + \\ & \operatorname{Tr}((\mathbf{g}^{-1}(\mathbf{Y}_1))^T (\mathbf{g}^{-1}(\mathbf{S}^\sharp))) - \operatorname{Tr}((\mathbf{g}^{-1}(\mathbf{Y}_1))^T \mathbf{S}) + \langle \mathbf{Y}_2, \mathbf{S} - \mathbf{S}\mathbf{C}_1 \rangle + \frac{\beta}{2} \|\mathbf{S} - \mathbf{S}\mathbf{C}_1\|_{\mathbb{F}}^2. \quad (1) \\ = \operatorname{argmin}_{\mathbf{S}} & \frac{1}{2} \|\mathbf{W} - \mathbf{R}\mathbf{S}\|_{\mathbb{F}}^2 + \frac{\beta}{2} (\|\mathbf{S}\|_{\mathbb{F}}^2 - 2\operatorname{Tr}((\mathbf{g}^{-1}(\mathbf{S}^\sharp))^T \mathbf{S}) - \frac{2}{\beta} \operatorname{Tr}((\mathbf{g}^{-1}(\mathbf{Y}_1))^T \mathbf{S})) + \\ & \langle \mathbf{Y}_2, \mathbf{S} - \mathbf{S}\mathbf{C}_1 \rangle + \frac{\beta}{2} \|\mathbf{S} - \mathbf{S}\mathbf{C}_1\|_{\mathbb{F}}^2. \left\{ \mathbf{S}^\sharp, \mathbf{Y}_1 \text{ are constants when minimizing over } \mathbf{S} \right\} \end{aligned}$$

Since, adding constants to the above form will not affect the solution of \mathbf{S} .

Therefore, we are adding $\|\mathbf{g}^{-1}(\mathbf{S}^\sharp) + \frac{\mathbf{g}^{-1}(\mathbf{Y}_1)}{\beta}\|_{\mathbb{F}}^2$ inside the second term,

which will give us the form

$$\begin{aligned} \mathbf{S} = \operatorname{argmin}_{\mathbf{S}} & \frac{1}{2} \|\mathbf{W} - \mathbf{R}\mathbf{S}\|_{\mathbb{F}}^2 + \frac{\beta}{2} \|\mathbf{S} - (\mathbf{g}^{-1}(\mathbf{S}^\sharp) + \frac{\mathbf{g}^{-1}(\mathbf{Y}_1)}{\beta})\|_{\mathbb{F}}^2 + \langle \mathbf{Y}_2, \mathbf{S} - \mathbf{S}\mathbf{C}_1 \rangle + \\ & \frac{\beta}{2} \|\mathbf{S} - \mathbf{S}\mathbf{C}_1\|_{\mathbb{F}}^2. \end{aligned}$$

The closed form solution for \mathbf{S} can be derived by taking derivative of (1) w.r.t to \mathbf{S} and equating to zero.

$$\frac{1}{\beta}(\mathbf{R}^T \mathbf{R} + \beta \mathbf{I})\mathbf{S} + \mathbf{S}(\mathbf{I} - \mathbf{C}_1)(\mathbf{I} - \mathbf{C}_1^T) = \frac{1}{\beta}\mathbf{R}^T \mathbf{W} + \left(\mathbf{g}^{-1}(\mathbf{S}^\sharp) + \frac{\mathbf{g}^{-1}(\mathbf{Y}_1)}{\beta} - \frac{\mathbf{Y}_2}{\beta}(\mathbf{I} - \mathbf{C}_1^T) \right). \quad (2)$$

1.2 Solution for \mathbf{S}^\sharp

$$\begin{aligned} \mathbf{S}^\sharp = \operatorname{argmin}_{\mathbf{S}^\sharp} & \langle \mathbf{Y}_1, \mathbf{S}^\sharp - \mathbf{g}(\mathbf{S}) \rangle + \frac{\beta}{2} \|\mathbf{S}^\sharp - \mathbf{g}(\mathbf{S})\|_F^2 + \langle \mathbf{Y}_3, \mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2 \rangle + \\ & \frac{\beta}{2} \|\mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2\|_F^2 + \langle \mathbf{Y}_8, \mathbf{S}^\sharp - \mathbf{J} \rangle + \frac{\beta}{2} \|\mathbf{S}^\sharp - \mathbf{J}\|_F^2. \end{aligned}$$

Here, also the first two term and last two terms is condensed to a simpler form for mathematical convenience without affecting the final solution.

$$\begin{aligned} \mathbf{S}^\sharp = \operatorname{argmin}_{\mathbf{S}^\sharp} & \operatorname{Tr}(\mathbf{Y}_1^T \mathbf{S}^\sharp) - \operatorname{Tr}(\mathbf{Y}_1^T \mathbf{g}(\mathbf{S})) + \frac{\beta}{2} (\|\mathbf{S}^\sharp\|_F^2 + \|\mathbf{g}(\mathbf{S})\|_F^2 - 2\operatorname{Tr}((\mathbf{S}^\sharp)^T \mathbf{g}(\mathbf{S}))) \\ & + \langle \mathbf{Y}_3, \mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2 \rangle + \frac{\beta}{2} \|\mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2\|_F^2 + \operatorname{Tr}(\mathbf{Y}_8^T \mathbf{S}^\sharp) - \operatorname{Tr}(\mathbf{Y}_8^T \mathbf{J}) + \frac{\beta}{2} (\|\mathbf{S}^\sharp\|_F^2 + \|\mathbf{J}\|_F^2 + \\ & - 2\operatorname{Tr}((\mathbf{S}^\sharp)^T \mathbf{J})). \end{aligned}$$

Since, we are minimizing over \mathbf{S}^\sharp . The terms which are not dependent on \mathbf{S}^\sharp can be considered as constants, which gives us:

$$\begin{aligned} \mathbf{S}^\sharp = \operatorname{argmin}_{\mathbf{S}^\sharp} & \frac{\beta}{2} (\|\mathbf{S}^\sharp\|_F^2 - 2\operatorname{Tr}(\mathbf{S}^\sharp)^T (\mathbf{g}(\mathbf{S}) - \frac{\mathbf{Y}_1}{\beta})) + \langle \mathbf{Y}_3, \mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2 \rangle + \frac{\beta}{2} \|\mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2\|_F^2 \\ & + \frac{\beta}{2} (\|\mathbf{S}^\sharp\|_F^2 - 2\operatorname{Tr}(\mathbf{S}^\sharp)^T (\mathbf{J} - \frac{\mathbf{Y}_8}{\beta})). \end{aligned}$$

Adding $\|\mathbf{g}(\mathbf{S}) - \frac{\mathbf{Y}_1}{\beta}\|_F^2$ and $\|\mathbf{J} - \frac{\mathbf{Y}_8}{\beta}\|_F^2$ inside the first term and last term

respectively to get the quadratic form. As these terms are constants when minimizing over \mathbf{S}^\sharp it will not affect the final solution.

$$\begin{aligned} \mathbf{S}^\sharp = \operatorname{argmin}_{\mathbf{S}^\sharp} & \frac{\beta}{2} \|\mathbf{S}^\sharp - (\mathbf{g}(\mathbf{S}) - \frac{\mathbf{Y}_1}{\beta})\|_F^2 + \langle \mathbf{Y}_3, \mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2 \rangle + \frac{\beta}{2} \|\mathbf{S}^\sharp - \mathbf{S}^\sharp \mathbf{C}_2\|_F^2 + \\ & \frac{\beta}{2} \|\mathbf{S}^\sharp - (\mathbf{J} - \frac{\mathbf{Y}_8}{\beta})\|_F^2. \end{aligned} \quad (3)$$

The closed form solution for \mathbf{S}^\sharp can be derived by taking derivative of (3) w.r.t \mathbf{S}^\sharp and equating to zero.

$$\mathbf{S}^\sharp (2\mathbf{I} + (\mathbf{I} - \mathbf{C}_2)(\mathbf{I} - \mathbf{C}_2^T)) = \left(\mathbf{g}(\mathbf{S}) - \frac{\mathbf{Y}_1}{\beta} \right) + \left(\mathbf{J} - \frac{\mathbf{Y}_8}{\beta} \right) - \frac{\mathbf{Y}_3}{\beta} (\mathbf{I} - \mathbf{C}_2^T). \quad (4)$$

1.3 Solution for C_1

$$\begin{aligned} C_1 &= \underset{C_1}{\operatorname{argmin}} \left\langle Y_2, S - SC_1 \right\rangle + \frac{\beta}{2} \|S - SC_1\|_F^2 + \left\langle Y_4, 1^T C_1 - 1^T \right\rangle + \\ &\quad \frac{\beta}{2} \|1^T C_1 - 1^T\|_F^2 + \left\langle Y_6, C_1 - E_1 \right\rangle + \frac{\beta}{2} \|C_1 - E_1\|_F^2. \\ &= \underset{C_1}{\operatorname{argmin}} \frac{\beta}{2} \|SC_1 - (S + \frac{Y_2}{\beta})\|_F^2 + \frac{\beta}{2} \|1^T C_1 - (1^T - \frac{Y_4}{\beta})\|_F^2 + \frac{\beta}{2} \|C_1 - (E_1 - \frac{Y_6}{\beta})\|_F^2. \end{aligned} \quad (5)$$

The closed form solution for C_1 is solved as:

$$(S^T S + 11^T + I) C_1 = S^T (S + \frac{Y_2}{\beta}) + 1(1^T - \frac{Y_4}{\beta}) + (E_1 - \frac{Y_6}{\beta}). \quad (6)$$

$$C_1 = C_1 - \operatorname{diag}(C_1), \quad (7)$$

1.4 Solution for C_2

$$\begin{aligned} C_2 &= \underset{C_2}{\operatorname{argmin}} \left\langle Y_3, S^\sharp - S^\sharp C_2 \right\rangle + \frac{\beta}{2} \|S^\sharp - S^\sharp C_2\|_F^2 + \left\langle Y_5, 1^T C_2 - 1^T \right\rangle + \\ &\quad + \frac{\beta}{2} \|1^T C_2 - 1^T\|_F^2 + \left\langle Y_7, C_2 - E_2 \right\rangle + \frac{\beta}{2} \|C_2 - E_2\|_F^2. \\ &= \underset{C_2}{\operatorname{argmin}} \frac{\beta}{2} \|S^\sharp C_2 - (S^\sharp + \frac{Y_3}{\beta})\|_F^2 + \frac{\beta}{2} \|1^T C_2 - (1^T - \frac{Y_5}{\beta})\|_F^2 + \frac{\beta}{2} \|C_2 - (E_2 - \frac{Y_7}{\beta})\|_F^2. \end{aligned} \quad (8)$$

The closed form solution for C_2 is derived as:

$$\left((S^\sharp)^T S^\sharp + 11^T + I \right) C_2 = (S^\sharp)^T (S^\sharp + \frac{Y_3}{\beta}) + 1(1^T - \frac{Y_5}{\beta}) + (E_2 - \frac{Y_7}{\beta}). \quad (9)$$

$$C_2 = C_2 - \operatorname{diag}(C_2), \quad (10)$$

1.5 Solution for E_1

$$\begin{aligned} E_1 &= \underset{E_1}{\operatorname{argmin}} \lambda_1 \|E_1\|_1 + \gamma_1 \|E_1\|_F^2 + \left\langle Y_6, C_1 - E_1 \right\rangle + \frac{\beta}{2} \|C_1 - E_1\|_F^2. \\ &= \underset{E_1}{\operatorname{argmin}} \lambda_1 \|E_1\|_1 + \gamma_1 \|E_1\|_F^2 + \frac{\beta}{2} \|E_1 - (C_1 + \frac{Y_6}{\beta})\|_F^2. \\ &= \underset{E_1}{\operatorname{argmin}} \lambda_1 \|E_1\|_1 + \gamma_1 \|E_1\|_F^2 + \frac{\beta}{2} \|E_1\|_F^2 - \beta < E_1, (C_1 + \frac{Y_6}{\beta}) > \\ &= \underset{E_1}{\operatorname{argmin}} \lambda_1 \|E_1\|_1 + (\gamma_1 + \frac{\beta}{2})(\|E_1\|_F^2 + \frac{2\beta}{2\gamma_1 + \beta} < E_1, C_1 + \frac{Y_6}{\beta} >). \\ &= \underset{E_1}{\operatorname{argmin}} \lambda_1 \|E_1\|_1 + (\gamma_1 + \frac{\beta}{2}) \|E_1 - \frac{\beta}{2\gamma_1 + \beta} (C_1 + \frac{Y_6}{\beta})\|_F^2. \end{aligned} \quad (11)$$

The closed form solution for E_1 is reached as:

$$E_1 = S \frac{\lambda_1}{\gamma_1 + \frac{\beta}{2}} \left(\frac{\beta}{2\gamma_1 + \beta} (C_1 + \frac{Y_6}{\beta}) \right) \quad (12)$$

1.6 Solution for E_2

The derivation for the solution of E_2 is similar to the solution of E_1 .

$$\begin{aligned} E_2 &= \underset{E_2}{\operatorname{argmin}} \lambda_3 \|E_2\|_1 + \gamma_3 \|E_2\|_F^2 + \langle Y_7, C_2 - E_2 \rangle + \frac{\beta}{2} \|C_2 - E_2\|_F^2 \\ &= \underset{E_2}{\operatorname{argmin}} \lambda_3 \|E_2\|_1 + (\gamma_3 + \frac{\beta}{2}) \|E_2 - \frac{\beta}{2\gamma_3 + \beta} (C_2 + \frac{Y_7}{\beta})\|_F^2. \end{aligned} \quad (13)$$

The closed form solution for E_2 is reached as:

$$E_2 = \mathcal{S}_{\frac{\lambda_3}{\gamma_3 + \frac{\beta}{2}}} \left(\frac{\beta}{2\gamma_3 + \beta} (C_2 + \frac{Y_7}{\beta}) \right). \quad (14)$$

2 Tables for each comparison

Table 1. Table corresponding to Figure 7

Datasets	BMM	PND	Zhu et al.	Kumar et al. [1]	Ours
Dance+Yoga	0.045	0.078	0.052	0.046	0.043
Drink+Walking	0.074	0.060	0.083	0.073	0.071
Shark+Stretch	0.024	0.015	0.067	0.025	0.019
Walking+Yoga	0.070	0.072	0.087	0.070	0.066
Face+Pickup	0.032	0.012	0.018	0.025	0.022
Face+Yoga	0.017	0.010	0.028	0.019	0.017
Shark+Yoga	0.035	0.018	0.094	0.037	0.033
Stretch+Yoga	0.039	0.109	0.045	0.039	0.036

Table 2. Table corresponding to Figure 8

Datasets	BMM	PND	Zhu et al.	Kumar et al. [1]	Ours
p2_free_2	0.1973	0.1544	0.1142	0.1992	0.1171
p2_grab_2	0.2018	0.1570	0.0960	0.2080	0.0822
p3_ball_1	0.1356	0.1477	0.0832	0.1348	0.0810
p4_meet_12	0.0802	0.0862	0.0972	0.0821	0.0815
p4_table_12	0.2313	0.1588	0.1322	0.2313	0.0994

Table 3. Table corresponding to Figure 11

Datasets	BMM	PND	Zhu et al.	Kumar et al. [1]	Ours
Face Sequence 1	0.078	0.077	0.082	0.075	0.073
Face Sequence 2	0.059	0.062	0.063	0.050	0.052
Face Sequence 3	0.042	0.051	0.057	0.038	0.039
Face Sequence 4	0.049	0.041	0.056	0.044	0.040

References

1. Kumar, S., Dai, Y., Li, H.: Multi-body non-rigid structure-from-motion. arXiv preprint arXiv:1607.04515 (2016)
2. Kumar, S., Dai, Y., Li, H.: Spatial-temporal union of subspaces for multi-body non-rigid structure-from-motion. arXiv preprint arXiv:1705.04916 (2017)